

Alternation conditions for multivariate approximation

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Introduction

We are interested in the problem of *finding the best uniform approximation of a continuous function f by a polynomial of degree at most n* :

$$\text{minimise } \|p - f\|_{\infty} \text{ subject to } p \in \Pi_n[x_1, \dots, x_d],$$

where

- Π_n is the set of polynomials of the variables x_1, \dots, x_d of degree at most n .
- $f: \mathbb{R}^d \rightarrow \mathbb{R}$ and bounded.

Preliminary considerations: the good

- Π_n is a linear vector space: $\forall p \in \Pi_n$

$$p(x_1, \dots, x_d) = \sum_{i \in I} a_i x^{\mathbf{i}}$$

where $\mathbf{i} = (i_1, \dots, i_d)$, $I = \{\mathbf{i} : i_1 + \dots + i_d \leq n\}$ and $x^{\mathbf{i}} = x_1^{i_1} x_2^{i_2} \dots x_d^{i_d}$.

- The objective function of the problem is proper convex.

Preliminary considerations: the bad

- dimension of the problem can be very large: $\binom{d+n}{d}$
- objective function is not differentiable
- problem is not separable

It is not possible to solve this problem except for very low values of n or d .

Question

How can we address the curse of dimensionality for this problem?

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Can we replace that question with another question? Yes!

Existing results

Case $d = 1$

Theorem (Chebyshev)

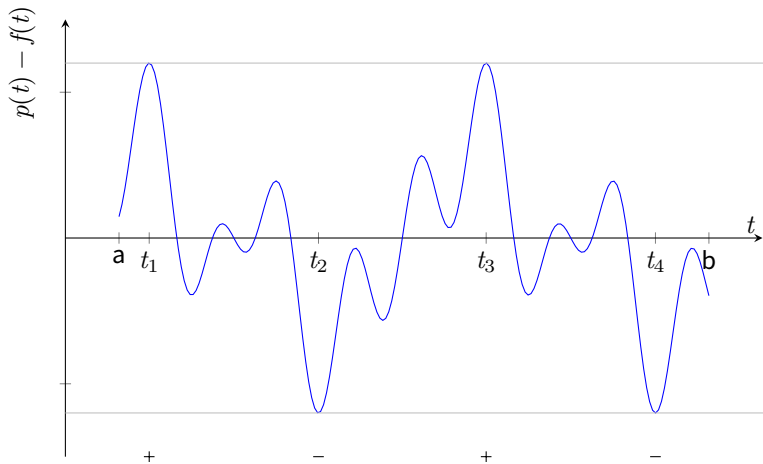
A polynomial $p \in \Pi_n[x]$ is a best uniform approximation of a continuous function $f: \mathbb{R} \rightarrow \mathbb{R}$ on an interval $[a, b]$ if and only if there exists $n + 2$ points $a \leq t_1 < \dots < t_{n+2} \leq b$ and a number $\sigma \in \{-1, 1\}$ such that $f(t_i) - p(t_i) = \sigma^i \|f - p\|_\infty$.

Definition (Extreme point)

- Points where the maximal deviation is attained are **extreme points**. We denote them $E^+(p)$ and $E^-(p)$.
- Points t_1, \dots, t_n for an **alternating sequence** of extreme points.

Existing results

Case $d = 1$



Existing results

Case $n = 1$

Theorem

A linear function is a best linear approximation of a function $f: \mathbb{R}^d \rightarrow \mathbb{R}$ if and only if $\text{co } E^+(p) \cap \text{co } E^-(p) \neq \emptyset$.

Existing results

Case $n = 1$

Examples with $d = 2$:

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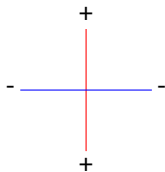
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Existing results

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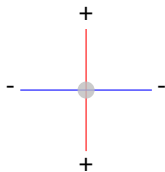
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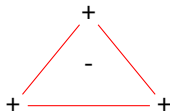
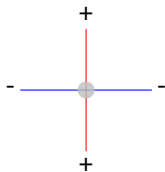
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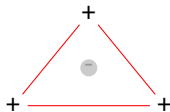
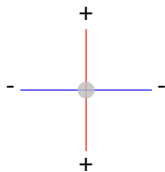
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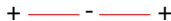
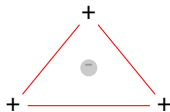
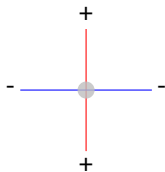
Examples with $d = 2$:



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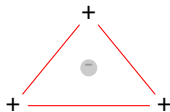
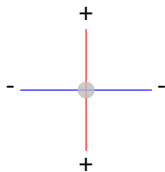
Examples with $d = 2$:



Existing results

Case $n = 1$

Examples with $d = 2$:



Some observations

- Two different spaces: \mathbb{R}^d and $\mathbb{R}^{\binom{d+n}{d}}$

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- Two different spaces: \mathbb{R}^d and $\mathbb{R}^{\binom{d+n}{d}} = \begin{cases} \mathbb{R}^{n+1} & \text{if } d = 1 \\ \mathbb{R}^{d+1} & \text{if } n = 1 \end{cases}$
- Characterisations are geometrical
- In terms of extreme points

Questions

- Can we provide a geometrical characterisation of best approximants for general degree n and dimension d ?
- What is the relationship of these characterisations with the notion of alternation?

Characterising solutions

Define by $M^n(\mathbf{x})$ the set of all monomials of degree at most n of \mathbf{x} . If $d = 2$,

$$M^2(\mathbf{x}) = \begin{pmatrix} 1 \\ x_1 \\ x_2 \\ x_1^2 \\ x_1 x_2 \\ x_2^2 \end{pmatrix},$$

Remark

$$M^1(\mathbf{x}) = \mathbf{x}$$

Characterising solutions

Theorem

A linear function is a best linear approximation of a function $f: \mathbb{R}^d \rightarrow \mathbb{R}$ if and only if

$$\text{co}\{M^n(\mathbf{x}) : \mathbf{x} \in E^+(p)\} \cap \text{co}\{M^n(\mathbf{x}) : \mathbf{x} \in E^-(p)\} \neq \emptyset$$

Proof.

Convex analysis/subdifferential calculus



Reducing the dimension

Theorem

Given a hyperplane \mathcal{H} separating two half-spaces \mathcal{H}^+ and \mathcal{H}^- . If p is a best uniform approximation in $\Pi^n[\mathbf{x}]$, then

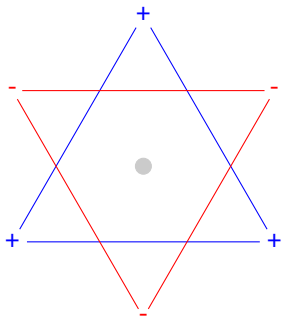
$$\text{co}\{M^{n-1}(\mathbf{x}) : \mathbf{x} \in E_{\mathcal{H}}^+(p)\} \cap \text{co}\{M^{n-1}(\mathbf{x}) : \mathbf{x} \in E_{\mathcal{H}}^-(p)\} \neq \emptyset$$

$$E_{\mathcal{H}}^+(p) = E^+(p) \cap \mathcal{H}^+ \cup E^-(p) \cap \mathcal{H}^-$$

$$E_{\mathcal{H}}^-(p) = E^-(p) \cap \mathcal{H}^+ \cup E^+(p) \cap \mathcal{H}^-$$

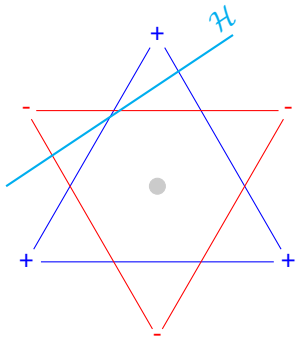
Reducing the dimension

Example for $n = 2$ and $d = 2$



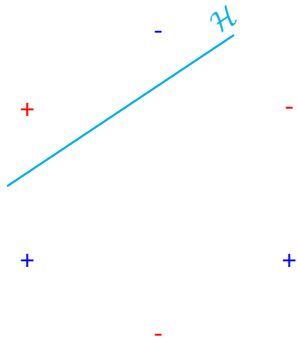
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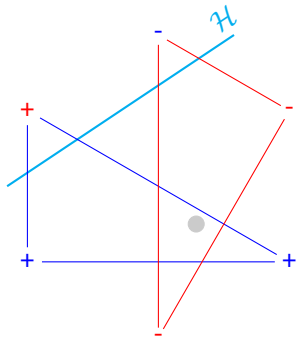
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Reducing the dimension: sufficiency

Theorem

If

$$\text{co}\{M^{n-1}(\mathbf{x}) : \mathbf{x} \in E_{\mathcal{H}}^+(p)\} \cap \text{co}\{M^{n-1}(\mathbf{x}) : \mathbf{x} \in E_{\mathcal{H}}^-(p)\} \neq \emptyset$$

for any hyperplane \mathcal{H} then p is a best approximation.

Relation to alternation

+ - + - + -

Relation to alternation

+ - | + - + -

Relation to alternation

- + | + - + -

Relation to alternation

↓ ↓ | ↓ ↓ ↓
- + + - + -

Relation to alternation

\downarrow \downarrow $+$ \downarrow \downarrow \downarrow
 $-$ $+$ $+$ $-$ $+$ $-$

Reducing the dimension

Theorem

Select d extreme points. If p is a best uniform approximation in $\Pi^n[\mathbf{x}]$, then

$$\text{co}\{M^{n-1}(\mathbf{x}) : \mathbf{x} \in E_{\mathcal{H}}^+(p)\} \cap \text{co}\{M^{n-1}(\mathbf{x}) : \mathbf{x} \in E_{\mathcal{H}}^-(p)\} \neq \emptyset$$

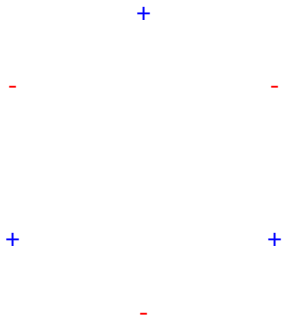
where \mathcal{H} is a hyperplane containing these points. Note that these d points are not in $E_{\mathcal{H}}^+(p)$ or in $E_{\mathcal{H}}^-(p)$.

Theorem

If the above result is true for any d extreme points, then p is a best approximation.

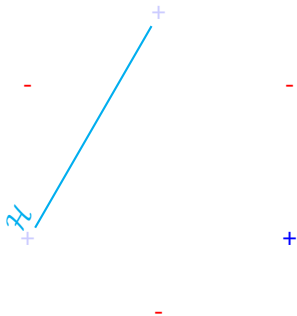
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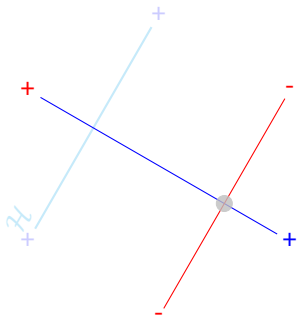
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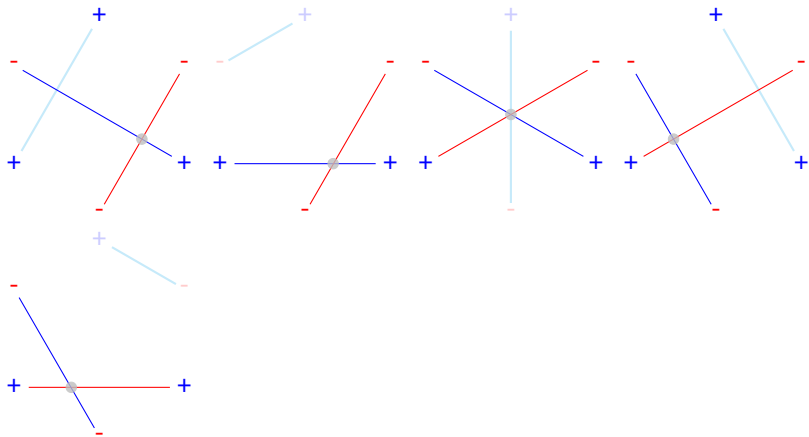


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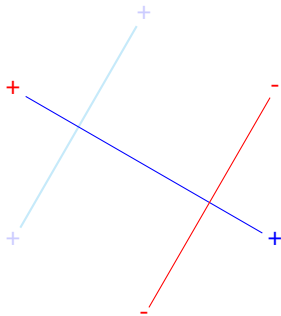


A “geometric” characterisation



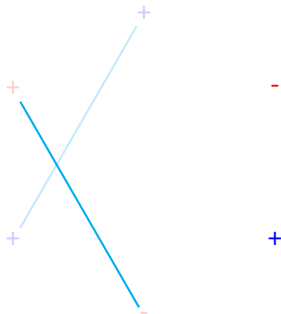
Reducing the dimension

Example for $n = 3$ and $d = 2$



Reducing the dimension

Example for $n = 3$ and $d = 2$



A conceptual algorithm...

Conceptual algorithm

repeat $n - 1$ times

- Step 1.** | Select d points and a hyperplane \mathcal{H} containing them
- Step 2.** | Update the signs of the remaining points according to \mathcal{H}
-

We need to apply this algorithm $\frac{((n-1)d)!}{(d!)^{n-2}} \binom{N}{(n-1)d}$ times.

Tentative definition of alternation...

Definition (alternating sequence)

A set of k points in \mathbb{R} alternates if by removing any point from the set one obtains an alternating set of $k - 1$ points by inverting the signs of the points on one side of the removed point.

Tentative definition of alternation...

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A set of k points in \mathbb{R} alternates if by removing any point from the set one obtains an alternating set of $k - 1$ points by inverting the signs of the points on one side of the removed point.

Definition (Generalised alternation)

A set of k points in \mathbb{R}^d alternate if by removing any d point from the set one obtains a set of $k - d$ points by inverting the signs of the points on one side of (a hyperplane containing) the removed point.

Future research

- We have an algorithm, but it is not practical.
- Do we need to consider all possible combinations of d points?
- Could it be that we only need to consider **facets** of the polytope formed by the extreme points? (Or maybe find a counter-example?)
- How does this compare against checking a simple intersection in a (much larger) space?